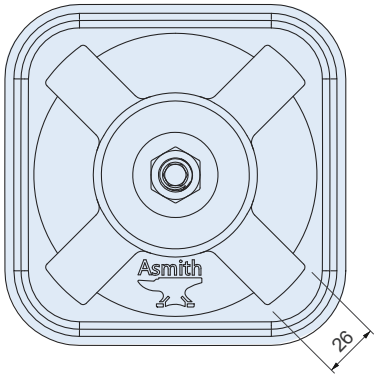
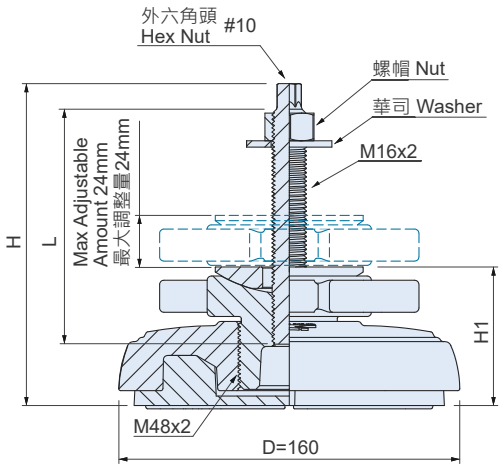
DK-0716110U

單支荷重 1300Kgf
Load Capacity 1300Kgf / each





材質與表面處理

- 盤座：FC-250 粉體烤漆(砂黑)
- 螺桿：S45C 熱處理及磷酸錳
- 盤墊：CR 合成橡膠(黑)

特徵

- 當作業場所地面傾斜不平時，自動導正水平角度。
- 確保機械精準度，以防止滑動。
- 防止機械於動作時產生過大震動，改善作業場所環境。
- 防止樓層因機械動作時產生共震、引震、噪音。
- 機器安裝時，可有效導正腳座盤墊面全部伏貼地面，穩定機械運轉。
- 機械腳放到盤座上，在容許荷重下壓時，可用開口板手在每一調整腳順利調整高度及水平。(如上圖所示)
- 防震、防滑、耐磨損、耐油。

MATERIAL AND FINISH

- Base: FC-250 Powder coating (Black)
- Bolt: S45C with heat treatment and coating with Manganese phosphate
- Cushion: Chloroprene Rubber (Black)

FEATURES

- Automatic adjust the horizontal angle.
- To ensure the precision of machinery in order to prevent from the slipping out.
- To prevent from the vibration and improve the work environment when the machine is on.
- To decrease the vibration between floors when the machine is running.
- To direct the support of machine on the ground correctly when the machine is installed.
- Smoothly adjust the machine height by the open-end wrench, when machine load on the Heavy-Duty Leveling Glide. (please refer to photo above)
- Resistance to shock, slip, abrasion and greasiness.

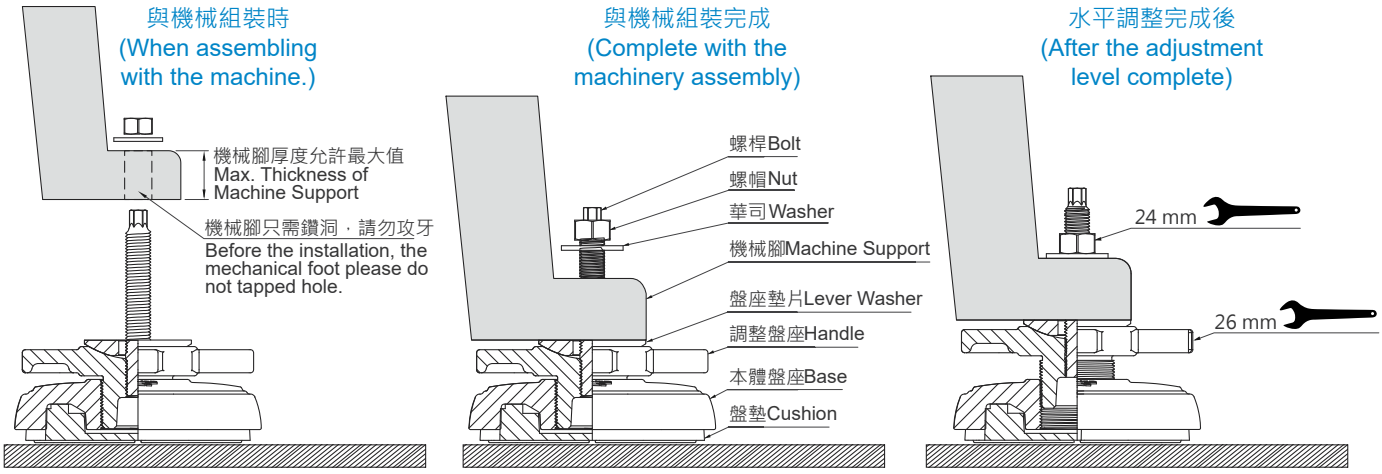
SPECIFICATION:

Unit: mm

產品編號 Item no.	尺寸 Dimensions				機械腳厚度允許最大值 Max. Thickness of Machine Support	最大調整量 Max. Adjustable Amount	荷重 Load Capacity (kgf)	重量 Weight (kg)
	D	L	H	H1				
DK-0716110U	160	110	151	65	55	24	1300	4.6
DK-0716200U		200	241		145			4.7

※Note : Before the installation, the mechanical foot please do not tapped hole.

※注意事項：安裝前，機械腳請勿攻牙。



使用說明

- 將盤座墊片放在腳座上，再將機械緩緩降下。
  (安裝前，機械腳只需鑽洞，請勿攻牙。)
- 螺桿由上側穿過機械腳及盤座墊片鎖入調整盤座中，再由上放入華司和螺帽。
- 用26mm開口扳手轉動調整盤座，調整出機械適當的高度及水平。
- 完成後將上方華司和螺帽鎖緊。

User Manual

- Place the level washer on the glide then lower down machine slowly. (Before the installation, the mechanical foot please do not tapped hole.)
- Insert the bolt through the machine into the glide then place the nut and washer from the top.
- To adjust machine to its height with the handle by the wrench(26mm).
- To tie the nut and washer when the adjustment is done accurately.

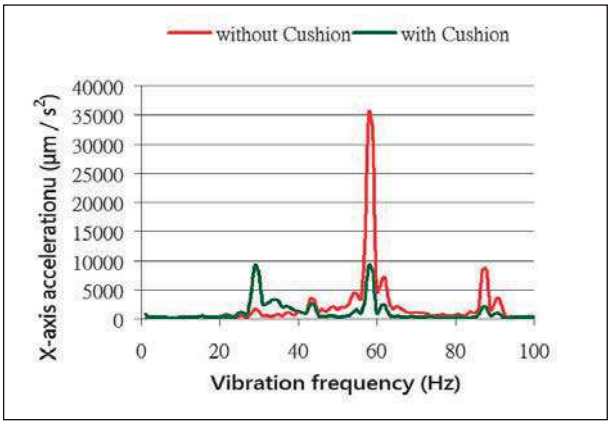
《測試結果．RESULT》

為隔振前(無隔振腳墊)
Before the Vibration isolation (without Cushion)

為隔振後(有隔振腳墊)
After the Vibration isolation (with Cushion)

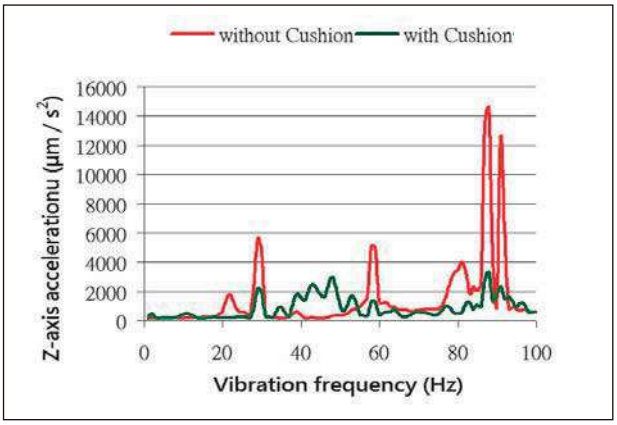
1. X方向隔振前(無隔振腳墊)與隔振後(有隔振腳墊)之加速度

1. X direction before the Vibration isolation (without Cushion) and after the Vibration isolation (with Cushion) of the acceleration.



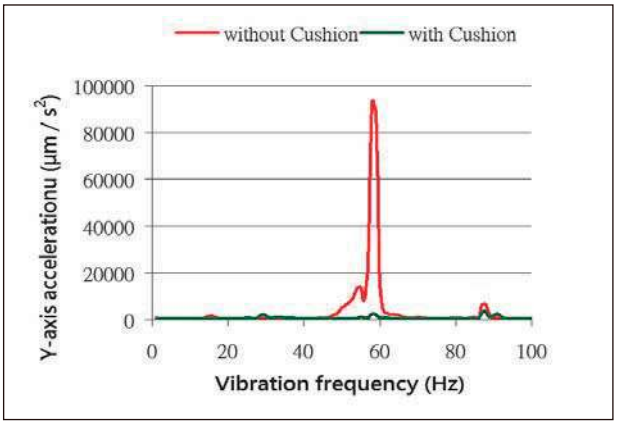
3. Z方向隔振前(無隔振腳墊)與隔振後(有隔振腳墊)之加速度

3. Z direction before the Vibration isolation (without Cushion) and after the Vibration isolation (with Cushion) of the acceleration.



2. Y方向隔振前(無隔振腳墊)與隔振後(有隔振腳墊)之加速度

2. Y direction before the Vibration isolation (without Cushion) and after the Vibration isolation (with Cushion) of the acceleration.



測試結果 RESULT	最大荷重(Kgf) Max. Load Capacity	最大位移(mm) Max. Shift
	1307.57	2.692